

# Shrish Choudhary

Fremont, CA | 510-509-0820 | Shrishc@mit.edu | [Portfolio](#) | [GitHub](#) | [LinkedIn](#)

## Education

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Massachusetts Institute of Technology, Cambridge, MA

Expected Graduation, May 2027

- BS in **Computer Science and Management**
- GPA: 4.7/5.0
- *Related Coursework:* Robotic Manipulation, Design and Analysis of Algorithms, Machine Learning, Software Construction, Computer Systems, Computer Vision, Computation Structures

## Experience

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Improbable AI Lab, Cambridge, MA

August 2025 – Present

Undergraduate Researcher

- Isaac lab simulation-based learning to teach robotic hands to understand shapes of objects through tactile sensors
- Expanded research into latent understanding with VAEs and diffusion models

eBay, San Jose, CA

May 2025 – August 2025

Machine Learning Intern

- Leveraged XGB and deep learning architectures to personalize checkout flows for billions of users
- Deployed **first ML pipeline to production** in payments, boosting checkout conversion by **22%**

Theoretical Physics Lab, Cambridge, MA

June 2024 – June 2025

Undergraduate Researcher – Head Engineer

- **2<sup>nd</sup> author** on publication, **secured** patent for \$2B addressable market
- Implemented stereo vision system with LiDAR 6D pose estimation and RL policy for navigation

MIT Edgerton Center, Cambridge, MA

November 2023 – May 2024

Undergraduate Researcher

- Adapted model to run locally using *TensorFlow lite* with an 85% accuracy
- Partnered with **Harvard Medical School** to deploy to rural villages

## Projects

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YC IAP Program Grant

December 2025 – January 2026

- Created 2d to 3d pipeline from listing to model for online shopping: [Mirim](#)
- Trained on-device models using distillation and Yolo for proactive safety: [Skeye](#)

Smartform

January 2025 – August 2025

- Developed **AI-powered analytics app** using visual ML models to deliver **medically validated** feedback
- Adopted by **200+ users**; received accelerator funding

Tennis Roomba

February 2024 – January 2025

- **Invented** robot with 360-degree movement to autonomously collect tennis balls
- **Combined** *PID* controls and on-device object recognition models to navigate courts

## Awards & Accomplishments

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- **YC IAP Program Grant Recipient** December 2025
- **Second Author - Science & CLEO Publications** May 2025
- **Autonomous Optical Assembly Patent Holder** January 2025
- **Eagle Scout** May 2020

## Skills

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- **Languages:** Python, C++, C, Java, Verilog, Assembly, SQL, Swift, Julia
- **Frameworks/Platforms:** PyTorch, TF, OpenCV, Isaac Sim, Isaac Gym, Drake, Git, Unity, PostgreSQL, AWS